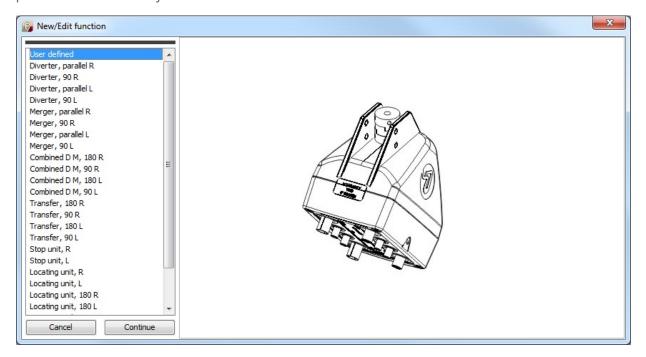
# User defined variant

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### **Background**

The x45e units is mainly set as standard functions via the wizard. But it is also possible to use the function unit as a generic control. In these cases the wizard could be used to set the unit to *User defined*. Then it is possible to go into the *Advanced* mode (*Tools* menu or *CTRL* + *A*)and set all parameters individually.



#### **Function mode**

The Function mode parameter describes the group of functions the unit should act as.

- 1= Diverter
- 2= Mergers & Combined Diverter/Mergers
- 3 = Transfers & Stop units & Locating units
- 4 = Postition mode (described in a separate article)
- 5 = Speed mode (described in a separate article)

## Function parameter / value

The x45e function unit is continuously running a sequence with three different step (Preturn / During production (Turn) / Post Turn). At start up it is always passing an Init state. There are four different function parameters. They are controlling how the unit should behave in all four sequence steps mentioned above.

## **Trigger**

Some times the unit start to move directly when entering a new sequence state. But if wanted it could also be triggered by a defined condition. Typically it is a sensor event (Digital Input 1-4) or a PLC command (External command). The External command is the control bits sent from the PLC. (External command is described as the binary value of the control byte, 4 means the bits should be 0000 0100).

See User Documentation - Electrical System for deeper description.

#### **Direction**

The function unit could be set to either Clockwise or Counter Clockwise. In some case it could be set to both (CW/CCW). Then the Extra field contains a comment.

#### **Destination**

The Destination is defining the target position for the movement.

INA = Receive Angle 1

INB = Receive Angle 2

INC = Receive Angle 3

OUTA = Release Angle 1

OUTB = Release Angle 2

WAA = Wait Angle 1

WAB = Wait Angle 2

### **Speed**

The unit has two speed setpoint. They are mainly differed regarding if the guide disc is supposed to move a puck or rotate empty. In some variants the speed setpoint is filled in explicitly.

#### Extra

If a comment is needed the Extra field is used.

Some variants have a built in delay:

- Timer A is the timer used for During production (Turn).
- Timer B is the timer used for Post Turn.
- Timer E is the timer used for Pre Turn.

# Diverter

Function parameter	value	Trigger	Direction	Destination	Speed	Extra	Extra	
1: Init	1		CCW	INA				
	2		CW	INA				
	3		CW	OUTA	ĝ i			
	4		CCW	OUTA				
8	1	DI1		INA				
	2	DI1	CW	INA	<u> </u>	s	00.000	
	3	DI1	CW/CCW		_	Direction = san	ne as last movement	
	4	DI3	CCW	INA				
2: Pre turn	5	DI3	CW	INA				
2. I le tuili	6	DI3	CW/CCW	INA	)	Direction = san	ne as last movement	
	7	External command = 4	CCW	INA	2 :			
	8	External command = 4	CW	INA				
	9	External command = 4	CW/CCW	INA		Direction = san	ne as last movement	
	10	External command = 1 or 2	20			Jump to during prod		
-	1	DI3		OUTA		Every other time	Time A delay	
		DIS	CW	OUTB	9	Every other time	Time A delay	
	2	DI3	CW	OUTA		Every other time	Time A delay	
	2	DIS	CCW	OUTB		Every other time	Time A delay	
	3	DI3 and DI2	CCW	OUTA			Time A delay	
	3	DI3 and not DI2	CW	OUTB			Time A delay	
	4	DI3 and DI2	CW	OUTA			Time A delay	
	4	DI3 and not DI2	CCW	OUTB			Time A delay	
1011	5	DI3 and not DI2	CW	OUTA	2		Time A delay	
3: During production		DI3 and DI2	CCW	OUTB			Time A delay	
5. During production		DI3 and not DI2	CCW	OUTA			Time A delay	
	0	DI3 and DI2	CW	OUTB			Time A delay	
	7	DI3 & External command = 1	CCW	OUTA				
	,	DI3 & External command = 2	CW	OUTB	6			
	8	DI3 & External command = 1	CW	OUTA				
	0	DI3 & External command = 2	CCW	OUTB				
	9	External command = 1	CCW	OUTA				
	10	External command = 2	CW	OUTB	3			
		External command = 1	CW	OUTA		S.		
	10	External command = 2	CCW	OUTB				
	1	OUTA	CCW	WAA			Time B delay	
4: Post tum		OUTB	CW	WAB			Time B delay	
4. I USL LUITI	2	OUTA	CW	WAA			Time B delay	
	2	OUTB	CCW	WAB	9		Time B delay	

# Merger & Combined Merger/Diverter

nction parameter	value	Trigger	Direction	Destination	Extra	Extra
	1	***	CCW	OUTA		
1: Init	2		CCW	OUTB		
1. 11111	3			OUTA	closest	
35	4		CW/CCS	OUTB	closest	
10	1	DI1	CW	INA	3	
		DI2	CCW	INB	2	
	2	DI1	CCW	INA		
		DI2	CW	INB		
		DI1 and OUTA	CW	INA		
	3	DI1 and OUTB	CCW	INA	2	
	3	DI2 and OUTA	CCW	INC	0	
		DI2 and OUTB	CW	INC		
		DI1 and OUTA	CCW	INA		
	4	DI1 and OUTB	CW	INA		
	7	DI2 and OUTA	CW	INC	88	
		DI2 and OUTB	CCW	INC		
		Ext cmd = 4 and OUTA	CW	INA	25	
		Ext cmd = 4 and OUTB	CCW	INA		
	5	Ext cmd = 8 and OUTA	CCW	INB		
	5	Ext cmd = 8 and OUTB	CW	INB	× 1	
		Ext cmd = 16 and OUTA	CCW	INC	C.	
2: Pre turn		Ext cmd = 16 and OUTB	CW	INC		
2. Pre turn		Ext cmd = 4 and OUTA	CCW	INA		
		Ext cmd = 4 and OUTB	CW	INA		
	6	Ext cmd = 8 and OUTA	CW	INB	4	
	О	Ext cmd = 8 and OUTB	CCW	INB		
		Ext cmd = 16 and OUTA	CW	INC		
		Ext cmd = 16 and OUTB	CCW	INC		
		DI1 and OUTA	CW	INA		
	7	DI1 and OUTB	CCW	INA		
	/	DI2 and OUTA	CCW	INB	×	
	. 8	DI2 and OUTB	CW	INB		
		DI1 and OUTA	CCW	INA		
		DI1 and OUTB	CW	INA		
	8	DI2 and OUTA	CW	INB		
		DI2 and OUTB	CCW	INB	9	
	9	Ext cmd = 4	CW	INA	6	
		Ext cmd = 8	CCW	INB		
	10	Ext cmd = 4	CCW	INA		
		Ext cmd = 8	CW	INB		

		DI3	CCW	OUTA		Time A delay
	1	DI4	CW	OUTB		Time A delay
		DI3	CW	OUTA		Time A delay
	2	DI4	CCW	OUTB		Time A delay
		DI3	CCW	OUTB		Time A delay
	3	DI4	cw	OUTA	Y 30	Time A delay
		DI3	CW	OUTB		Time A delay
	4	DI4	CCW	OUTA		Time A delay
		DI3	CW	OUTB		Time A delay
	5	DI4	CW	OUTA	2.	Time A delay
	-	DI3	CCW	OUTB	· V	Time A delay
	6	DI4	CCW	OUTA		
		DI3 and Ext cmd = 1 and INA	CCW	OUTA		Time A delay
			CW	OUTA		2000 000
	7	DI4 and Ext cmd = 1 and (INB or INC) DI3 and Ext cmd = 2 and INA	CW	OUTB		
			CCW	OUTB		
		DI4 and Ext cmd = 2 and (INB or INC) DI3 and Ext cmd = 1 and INA	CCW	OUTA		
	8	DI4 and Ext cmd = 1 and (INB or INC) DI3 and Ext cmd = 2 and INA	CCW	OUTA		
		DI4 and Ext cmd = 2 and (INB or INC)  External command 1 & INA	CW	OUTB		
	9		CCW	OUTA	34	
		External command 1 & INB	CCW	OUTA	200	
	10	External command 1 & INA	CCW	OUTA		
3: During production		External command 1 & INB		OUTA		
		Ext cmd = 1 and INA	CCW	OUTA		
	11	Ext cmd = 1 and (INB or INC)	CW	OUTB		
	100	Ext cmd = 2 and INA	CCW	OUTB		
		Ext cmd = 2 and (INB or INC)  Ext cmd = 1 and INA	CW	OUTA		
			CCW	OUTA		
	12	Ext cmd = 1 and (INB or INC)	CCW	OUTB		
		Ext cmd = 2 and INA	CCW	OUTB		
		Ext cmd = 2 and (INB or INC)				
		Ext cmd = 1 and INA	CCW	OUTA		
	13	Ext cmd = 1 and (INB or INC)		OUTB		
		Ext cmd = 2 and INA	CCW			
		Ext cmd = 2 and (INB or INC)	CW	OUTB		
		Ext cmd = 1 and INA	CW	OUTA	9	
	14	Ext cmd = 1 and (INB or INC)	CCW	OUTA		
	777	Ext cmd = 2 and INA	CW	OUTB		
		Ext cmd = 2 and (INB or INC)	CCW	OUTB		
		DI3 (one to OUTA, one to OUTB)	CCW	OUTA		
	15	DILL CUTTO	CCW	OUTB		
		DI4 (one to OUTA, one to OUTB)	CW	OUTA	S1	
			CW	OUTB		
		DI3 (one to OUTA, one to OUTB)	CW	OUTA		
	16		CW	OUTB	- /-	
	10	DI4 (one to OUTA, one to OUTB)	CCW	OUTA		
9			CCW	OUTB		
4: Post tum	1		8		9	Time B delay

# **Transfers & Stop units & Locating units**

Function parameter	value	Trigger	Direction	Destination		Extra	Extra
1: Init	1		CCW	INA			
	2		CW	INA			
	3		CCW	OUTA	8 2		
I. IIIIC	4		CW	OUTA	9 9		
	5		CCW	OUTB	c s		
	6		CW	OUTB			
	1	DI1	CCW	WAA	Setpoint1		Time E delay
	2	DI1	CW	WAA	Setpoint1		Time E delay
	3	DI1	CCW	WAB	Setpoint1		Time E delay
	4	DI1	CW	WAB	Setpoint1		Time E delay
	5	DI1	CW	INA	Setpoint2		Time E delay
	6	DI1	CCW	INA	Setpoint2		Time E delay
	7	DI1 and External command = 4	CCW	INA	Setpoint2		
	8	DI1 and External command = 4	CW	INA	Setpoint2		
	9		CW	INA	Setpoint2		Time E delay
	10	7	CCW	INA	Setpoint2		Time E delay
	11	External command = 4	CCW	INA	Setpoint2		
	12	External command = 4	CW	INA	Setpoint2		
2: Pre turn	13	DI1and External command = 2 or 256, OUTB or WAA	CW	WAA	Setpoint1		
Z. FIE turn		DI1and External command = 1, OUTA	CCW	OUTA	Setpoint1		
	14	DI1and External command = 2 or 256, OUTB or WAA	CCW	WAA	Setpoint1		
		DI1and External command = 1, OUTA	CW	OUTA	Setpoint1		
	15	External command = 2 or 256, OUTB or WAA	CW	WAA	Setpoint1		
		External command = 1, OUTA	CCW	OUTA	Setpoint1		
	16	External command = 2 or 256, OUTB or WAA	CCW	WAA	Setpoint1		
	10	External command = 1, OUTA	CW	OUTA	Setpoint1		
	17	Timer if (puck in process); move if (DI3 or (puck in process and	CW	INB	9		
	18	Timer if (puck in process); move if (DI3 or (puck in process and	CCW	INB			
	19	DI2 (InPosition at INA) and (DI3 or (not DI3 and not DI1))	CW	INB			
	20	DI2 (InPosition at INA) and (DI3 or (not DI3 and not DI1))	CCW	INB			
	21	External command = 8 (INB)	CW	INB	× ×		
	22	External command = 8 (INB)	CCW	INB	9		

	1		CCW	OUTA	8	2	Time A delay
	2		CW	OUTA	l,	2	Time A delay
	3		CCW	OUTB			Time A delay
	4		CW	OUTB			Time A delay
	5	External command = 1	CW	OUTA		×	105
	6	External command = 1	CCW	OUTA		2	
	7	DI1	CCW	OUTB		·	Time A delay
	8	DI1	CW	OUTB			Time A delay
	9	DI2	CW	OUTA			
	10	DI2	CCW	OUTA		·	
3: During production	11	DI2	CW	OUTB	£	2	
3. During production	12	DI2	CCW	OUTB		χ	
	13	DI1	CW	OUTA			Time A delay
	14	DI1	CCW	OUTA			Time A delay
	15	External command = 2	CW	OUTB		·	19
	16	External command = 2	CCW	OUTB	4	2	
	17	Timer if (puck in process); move if (DI3 or (puck in process and	CW	INC			
	18	Timer if (puck in process); move if (DI3 or (puck in process and	CCW	INC			
	19	DI2 (InPosition at INB) and (DI3 or (not DI3 and not DI1))	CW	INC			
	20	DI2 (InPosition at INB) and (DI3 or (not DI3 and not DI1))	CCW	INC			
	21	External command = 16 (INC)	CW	INC		3	
	22	External command = 16 (INC)	CCW	INC			
Ø.	1		CCW	INA			Time B delay
	2		CW	INA		v.	Time B delay
	3		CCW	OUTA			Time B delay
	4		CW	OUTA			Time B delay
	5	External command = 4	CCW	INA	Setpoint2	×	100
	6	External command = 4	CW	INA	Setpoint2	2	
4: Post tum	7		CCW	OUTB		2	Time B delay
	8		CW	OUTB			Time B delay
	9	not DI2		stay			
	10			stav			
	11	Timer if (puck in process); move if (DI3 or (puck in process and	CW	INA		3	
	12	Timer if (puck in process); move if (DI3 or (puck in process and	CCW	INA			
	13	DI2 (InPosition at INC) and (DI3 or (not DI3 and not DI1))	CW	INA			
	14	DI2 (InPosition at INC) and (DI3 or (not DI3 and not DI1))	CCW	INA			
	15	External command = 4 (INA)	CW	INA	Setpoint1		
	16	External command = 4 (INA)	CCW	INA	Setpoint1	3	